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Authors: David Bieber,

Charles Sutton, Hugo

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Larochelle, Daniel

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[cs.NE] 17 Oct 2014.

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(Maddison &
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a language model on
parse trees, and (Mou
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Both of these
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them as a set of
points or a
composition of
geometric primitives:
we also effortlessly

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Understand higher-level shape structure such as the repetition and reflective symmetry of object parts. In contrast, recent advances in 3D shape sensing focus more on low-level geometry but less on these higher-level relationships. In this paper, we ...

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Learning to produce efficient movement behaviour for humanoid robots from

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scratch is a hard problem, as has been illustrated by the "Learning to run" competition at NIPS 2017. The goal of this competition was to train a two-legged model of a humanoid body to run in a simulated race course with maximum speed. All submissions took a tabula rasa approach

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We seek to efficiently
learn by leveraging
shared structure
between different
tasks and

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environments. For

example, cooking is similar in different kitchens, even though the ingredients may change location. In principle, meta-reinforcement learning approaches can exploit this shared structure, but in practice, they fail to adapt to new environments when

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~~Adaptation~~ requires
targeted exploration

...

~~[2008.02790] Explore
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reasoning, but they often fail to learn the abstract concepts underlying these algorithms. This is evidenced by their inability to generalize to data distributions that are outside of their restricted training sets, Page 2/8

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requirement. The
L2RPN competition
which we will present
and analyze here,
takes some
inspiration from the
Learning to run [14]
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goal was to learn a
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Recently we proposed the Span Attribute Tagging (SAT) Model Du et al. (2019) to infer clinical entities (e.g., symptoms) and their properties (e.g., duration). It tackles

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the challenge of large label space and limited training data using a hierarchical two-stage approach that identifies the span of interest in a tagging step and assigns labels to the span in a classification step.

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